**Calibration Procedure**

1. Use an angle measurement tool to measure the angles at where the servo is pointing.
2. Read on screen instructions, the servo should begin around angle 0.
3. If it is beyond zero in the positive direction press switch 2 to rotate the servo backwards
4. If it is behind zero then press switch 1 to rotate the servo forwards
5. When the servo is at the desired angle press switch 4
6. Repeat these steps for all the angle positions
7. The microcontroller will now preform its calculations
8. Running the check program should show the various positions